Preliminary Earthquake Detection and Location Using the Cascadia Iniative Amphibious Dataset Emily A. Morton(emorton@nmt.edu) and Susan L. Bilek



Subspace Detection

A portion of the data corresponding to a sliding window is projected onto a subspace spanned by the basis vectors. Comparison of the orignal windowed data with the projected data gives a z-statistic (like a correlation coefficient) for each step through the data.

For a given data file containing unknown signals, we end up with a distribution of correlation coefficients and/or z-statistics. Those above a chosen threshold likely correspond to events.

Signal model: <u>s</u> = <u>U</u> <u>a</u> [n] $\underline{U}^T \underline{U} = \underline{I}$

H₀: noise only

H₁: signal + noise

Figure 3. Modified from Harris [2006] and Harris and Paik [2006]. The subspace detector uses multiple template events to compare with the data containing unknown signals. An unknown signal, s, in the data can be represented by a linear combination of the basis vectors of the set of templates, U, with coefficients a[n].

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Implementation

We use land-seismometer based catalogs (NEIC , ANF, PNSN, and Canadian NEDB) to identifify clusters and individual interface earthquakes to use as templates.

We find these events on OBSs and few additional coastal land stations (Earthscope, Global Seismic Network, US National Seismic Network, U. Washington/Pacific NW Regional Seismic Network, and Canadian Seismic Network) to create templates.



Figure 5. Templates on OBS station M08A, highlighted in box on Figure 4. Earthquakes occurred March 12, 2012 - March 26, 2012 and range in magnitude from 1.9 to 3.7. Templates are high-passed filtered with corner frequency at 5 Hz.



Number of Unique Detections for Subset Year 1 Data: 263

M08A	J25A	102D
175	80	48

Figure 7. Subset of events detected on station M08A, aligned on P-arrival. High-pass filtered at 5 Hz.

Figure 6. Z-statistic distribution through time (a) and histogram of z-statistics (b) for the first weekd of data scanned for M08A (October 21, 2011 - October 27, 2011). Thresholds were chosen for each month of data scanned based on the z-statistcs from scanning the first week of each month. Here, the threshold is 0.05 (red line). For the first cluster, thresholds were chosen visuall. Subsequent cluster are chosen as ~14.55 or 10.08 (for OBS and land, respectively) standard deviations above the distribution mean, which was the mean trend of the cluster one thresholds.



Event Detection

▲ Stations (Year 1) Earthquakes During Year 1, M 0-6.5 **Earthquakes Chosen** as Templates

Figure 4. Map of seismicity during the first year of CI deployment with events used as templates highlighted by the box. Stations M08A, J25A, and I02D used for subspace detection.



coverage), and vertical errors range 1.4 to 99 km. Depths range -4.4 km to 30.0 km (negative values due to shifting station elevations to all positive values).



Conclusions / Future Work

During the first year of CI deployment, 263 events were detected with the target cluster templates on stations M08A, J25A, and I02D. We have preliminary locations for the 103 events that appear on multiple stations.

The majority of the new events are located within the target cluster, where previous repeaters have been observed [e.g. Trehu et al., 1994; 2008; 2012;2015; and Williams et al., 2011]

We will continue running detection codes using templates along the margin for all four years of deployment and locate all detected events along the CSZ, as well as compute source parameters of detected events.

Locations and source parameters will be compared to variations in overriding-plate geology and varying structure on the subducting plates.

Figure 9. Phase picks (red lines) for detected event on May 17, 2012 on OBS and land stations



-126°

–125°

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